# Dynamics of a membrane interacting with an active wall

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Active motions of a biological membrane can be induced by nonthermal fluctuations that occur in the outer environment of the membrane. We discuss the dynamics of a membrane interacting hydrodynamically with an active wall that exerts random velocities on the ambient fluid. Solving the hydrodynamic equations of a bound membrane, we first derive a dynamic equation for the membrane fluctuation amplitude in the presence of different types of walls. Membrane two-point correlation functions are calculated for three different cases: (i) a static wall, (ii) an active wall, and (iii) an active wall with an intrinsic time scale. We focus on the mean squared displacement (MSD) of a tagged membrane describing the Brownian motion of a membrane segment. For the static wall case, there are two asymptotic regimes of MSD ( $\sim t^{2/3}$  and  $\sim t^{1/3}$ ) when the hydrodynamic decay rate changes monotonically. In the case of an active wall, the MSD grows linearly in time ( $\sim t$ ) in the early stage, which is unusual for a membrane segment. This linear-growth region of the MSD is further extended when the active wall has a finite intrinsic time scale.

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I. INTRODUCTION

The random slow dynamics of fluid membranes visible as a flickering phenomenon in giant unilamellar vesicles (GUVs) or red blood cells (RBCs) has attracted many interests in the last few decades [1]. These thermally excited shape fluctuations can be essentially understood as a Brownian motion of a two-dimensional (2D) lipid bilayer membrane in a three-dimensional (3D) viscous fluid such as water. For spherically closed artificial GUVs, characteristic relaxation times for shape deformations were calculated analytically [2–5]. Analysis of shape fluctuations can be used for quantitative measurements of surface tension and/or bending rigidity of single-component GUVs [6] or GUVs containing bacteriorhodopsin pumps [7].

Historically, investigations on fluctuations of cell membranes have started with RBCs whose flickering can be observed under a microscope [8]. Brochard and Lennon were among the first to describe quantitatively membrane fluctuations as thermally excited undulations, mainly governed by the bending rigidity of the membrane [9]. Later experiments showed that flickering in RBCs is not purely of thermal origin but rather corresponds to a nonequilibrium situation because the fluctuation amplitude decreases upon ATP depletion [10,11]. Here ATP hydrolysis plays an important role to control membrane-spectrin cytoskeleton interactions [12]. More advanced techniques have demonstrated that, at longer time scales (small frequencies), a clear difference exists between the power spectral density of RBC membranes measured for normal cells and those ATP depleted; the fluctuation amplitude turns out to be higher in the former [13,14]. At shorter time scales, on the other hand, membranes fluctuate as in the thermodynamic equilibrium. It should be noted, however, that the role of ATP in flickering is still debatable because Boss et al. have recently claimed that the mean fluctuation amplitudes of RBC membranes can be described

by the thermal equilibrium theory, while ATP merely affects the bending rigidity [15].

In order to understand shape fluctuations of RBCs, one needs to properly take into account the effects of spectrin cytoskeleton network that is connected to the membrane by actin, glycophorin, and protein 4.1R [1,12]. Gov et al. treated the cytoskeleton as a rigid wall (shell) located at a fixed distance from the membrane and assumed that its static and dynamic fluctuations are confined by the cytoskeleton [16,17]. They further considered that the sparse connection of membrane and cytoskeleton gives rise to a finite surface tension for length scales larger than the membrane persistence length. The bending free energy for a membrane was extended to include a surface tension and a confinement potential with which the effects of ATP on the membrane fluctuations was described. However, since an active component of the membrane fluctuations also depend on the fluid viscosity [18], they cannot be solely attributed to the static parameters such as the surface tension or the potential. Gov and Safran later estimated the active contribution to the membrane fluctuations due to the release of stored tension in the spectrin filament and membrane in each dissociation event [19,20]. In contrast to static thermal fluctuations, they showed that the active cytoskeleton may contribute to the membrane fluctuations at intermediate length scales.

Effects of membrane confinement are important not only for shape fluctuations of RBCs but also for a hydrodynamic coupling between closely apposed lipid bilayer membranes [21,22], and dynamical transitions occurring in lamellar membranes under shear flow [23,24]. After the seminal works by Kramer [25] and by Brochard and Lennon [9], the wavenumber-dependent decay rate for the bending modes of a membrane bound to a wall was calculated by Seifert [26] and Gov *et al.* [17]. In particular, Seifert showed that the scale separation between the membrane-wall distance and the correlation length determined by the confinement potential can lead to various crossover behaviors of the decay rate. In these hydrodynamic calculations, however, the wall that interacts with the membrane was treated as a static object and does not play any active role.

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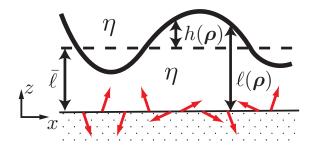


FIG. 1. A fluctuating membrane interacting with an active wall. The membrane separated by a distance  $\ell(\rho)$  from the wall feels a potential  $V(\ell)$  per unit area. The average of  $\ell(\rho)$  is  $\bar{\ell}$ , and the membrane fluctuation is defined by  $h(\rho) = \ell(\rho) - \bar{\ell}$ . Between the membrane and the wall as well as above the membrane are filled with a fluid of viscosity  $\eta$ . Red arrows on the wall indicate active velocities exerted on the fluid by the wall.

Quite generally, active motions of a membrane can be induced by nonthermal fluctuations that occur in the outer environment of the membrane such as cytoskeleton or cytoplasm. In this paper, we consider the dynamics of a membrane interacting with an active wall that generates random velocities in the ambient fluid. These random velocities at the wall can be naturally taken into account through the boundary conditions of the fluid. We first derive a dynamic equation for the membrane fluctuation amplitude in the presence of hydrodynamic interactions. Then we calculate the membrane two-point correlation functions for three different cases: (i) a static wall, (ii) an active wall, and (iii) an active wall with an intrinsic time scale. We especially focus on the mean squared displacement (MSD) of a tagged membrane segment and discuss its asymptotic time dependencies for the above cases. For the static wall case, the membrane fluctuates due to thermal agitations, and there are two asymptotic regimes of MSD  $(\sim t^{2/3} \text{ and } \sim t^{1/3})$  if the hydrodynamic decay rate changes monotonically as a function of the wave number. When the wall is active, there is a region during which the MSD grows linearly with time ( $\sim t$ ), which is unusual for a membrane segment. If the active wall has a finite intrinsic time scale, the above linear-growth regime of the MSD is further extended. As a whole, active fluctuations at the wall propagate through the surrounding fluid and greatly affects the membrane fluctuations.

This paper is organized as follows. In the next section, we discuss the hydrodynamics of a bound membrane that interacts with an active wall. We also derive a dynamic equation for the membrane fluctuation amplitude in the presence of hydrodynamic interactions. In Sec. III, we calculate the membrane two-point correlation functions for three different cases of the wall as mentioned above. We investigate various asymptotic behaviors of the MSD of a tagged membrane in both the static and the active wall cases. Some further discussions are provided in Sec. IV.

# II. HYDRODYNAMICS OF A BOUND MEMBRANE

### A. Free energy of a bound membrane

As depicted in Fig. 1, we consider a fluid membrane bound at an average distance  $\bar{\ell}$  from a wall which defines the xy

plane. Within the Monge representation, which is valid for nearly flat surfaces, the membrane shape is specified by the distance  $\ell(\rho) = \ell(x,y)$  between the membrane and the wall. The free energy F of a tensionless membrane in a potential  $V(\ell)$  per unit area reads [27,28]

$$F = \int d^2 \rho \left[ \frac{\kappa}{2} (\nabla^2 \ell)^2 + V(\ell) \right], \tag{1}$$

where  $\kappa$  is the bending rigidity and  $d^2\rho = dx\,dy$ . We use a harmonic approximation for fluctuations  $h(\rho) = \ell(\rho) - \bar{\ell}$  around the minimum of the potential at  $\ell = \bar{\ell}$  and obtain the approximated form

$$F \approx \frac{\kappa}{2} \int d^2 \rho \, [(\nabla^2 h)^2 + \xi^{-4} h^2],$$
 (2)

where  $\xi = [\kappa/(d^2V/d\ell^2)_{\ell=\bar{\ell}}]^{1/4}$  is the correlation length due to the potential. Later we use a dimensionless quantity defined by  $\Xi \equiv \xi/\bar{\ell}$  in order to discuss different cases.

In the following, we introduce the 2D spatial Fourier transform of  $h(\rho)$  defined as

$$h(\mathbf{q}) = \int d^2 \rho \, h(\mathbf{\rho}) e^{-i\mathbf{q}\cdot\mathbf{\rho}},\tag{3}$$

where  $\mathbf{q} = (q_x, q_y)$ . Then the static correlation function can be obtained from Eq. (2) as

$$\langle h(\boldsymbol{q})h(-\boldsymbol{q})\rangle = \frac{k_{\rm B}T}{\kappa(q^4 + \xi^{-4})} = \frac{k_{\rm B}T}{E(q,\xi)},\tag{4}$$

where  $k_{\rm B}$  is the Boltzmann constant, T the temperature,  $q = |\boldsymbol{q}|$ , and we have introduced the notation  $E(q,\xi) \equiv \kappa(q^4 + \xi^{-4})$ .

In the present model, we assume that the wall is rigid and does not deform. Even when the wall, mimicking the cytoskeleton network, is deformable, the above free energy [Eq. (1)] would not be changed if we regard  $\ell$  as a local distance between the membrane and the cytoskeleton. In this case, however, the bending rigidity  $\kappa$  should be replaced with an effective one which is also dependent on the bending rigidity of the cytoskeleton network itself [29].

# B. Hydrodynamic equations and boundary conditions

The dynamics of a membrane is dominated by the surrounding fluid, which is assumed to be incompressible and to obey the Stokes equation. We choose z as the coordinate perpendicular to the wall located at z=0 as in Fig. 1. Then the velocity  $v(\rho,z)$  and the pressure  $p(\rho,z)$  for  $z \neq \bar{\ell}$  satisfy the following equations:

$$\nabla \cdot \mathbf{v} = 0, \tag{5}$$

$$\eta \nabla^2 \boldsymbol{v} - \boldsymbol{\nabla} p - \boldsymbol{f} = 0, \tag{6}$$

where  $\eta$  is the viscosity of the surrounding fluid and  $f(\rho, z)$  is any force acting on the fluid. The fluid velocity can be obtained from the above equations by supplementing them with proper boundary conditions. In the Appendix, we show a formal solution appropriate for the membrane-wall system and obtain the fluid velocity  $\boldsymbol{v}$  in terms of the force f. Without loss of generality, we can choose the x and y coordinates as the parallel (longitudinal) and the perpendicular (transverse)

directions to the in-plane vector  $\mathbf{q}$ , respectively. Since the transverse y component of the velocity is not coupled to the other components, we are allowed to set  $v_y = 0$  in what follows

Let us denote the fluid regions  $0 \le z \le \bar{\ell}$  and  $\bar{\ell} \le z$  with the superscripts "—" and "+," respectively. In general, we consider time-dependent boundary conditions at z = 0 and time-independent conditions at  $z \to \infty$ :

$$v_{x}^{-}(\boldsymbol{q}, z = 0, t) = V_{x0}(\boldsymbol{q}, t),$$
 (7)

$$v_z^-(q, z = 0, t) = V_{z0}(q, t),$$
 (8)

$$v_x^+(q, z \to \infty, t) = v_z^+(q, z \to \infty, t) = 0.$$
 (9)

The statistical properties of  $V_{x0}(\boldsymbol{q},t)$  and  $V_{z0}(\boldsymbol{q},t)$  will be discussed for different types of walls in the next section. As described in the Appendix, the z component of the velocity is then obtained as

$$v_{z}^{-}(\boldsymbol{q},z,t) = A[\sinh(qz) - qz \cosh(qz)] + Bqz \sinh(qz) - iqzV_{x0}(\boldsymbol{q},t)e^{-qz} + (1+qz)V_{z0}(\boldsymbol{q},t)e^{-qz},$$
(1)

$$v_z^+(q,z,t) = Ce^{-q(z-\bar{\ell})} + Dq(z-\bar{\ell})e^{-q(z-\bar{\ell})},$$
 (11)

where A, B, C, and D are the coefficients determined by the other boundary conditions at the membrane  $z = \bar{\ell}$ . Note that both  $v_x$  and p can be also expressed in terms of these four coefficients.

At  $z = \bar{\ell}$  where the membrane exists, continuity of  $v_x$  and  $v_z$  yields

$$v_r^-(q, z = \bar{\ell}, t) = v_r^+(q, z = \bar{\ell}, t),$$
 (12)

$$v_z^-(q, z = \bar{\ell}, t) = v_z^+(q, z = \bar{\ell}, t),$$
 (13)

and incompressibility of the membrane requires that the inplane divergence of  $v_x$  vanishes:

$$iqv_{x}^{-}(q,z=\bar{\ell},t)=0.$$
 (14)

Moreover, the forces are required to balance in the normal direction at  $z = \bar{\ell}$ . This condition is written as

$$-T_{zz}^{+} + T_{zz}^{-} = -\frac{\delta F}{\delta h(q,t)} = -E(q,\xi)h(q,t), \quad (15)$$

where  $E(q,\xi)$  was defined in Eq. (4). In the above,  $T_{zz}^{\pm}$  is the Fourier transformed zz component of the fluid stress tensor

$$T_{ij} = -p\delta_{ij} + \eta(\partial_i v_j + \partial_j v_i), \tag{16}$$

evaluated at  $z = \bar{\ell} \pm 0$  and i, j = x, z. The above four boundary conditions in Eqs. (12)–(15) at  $z = \bar{\ell}$  determine the solution of v and p in the entire region of the fluid.

### C. Dynamic equation of a bound membrane

Next we derive a dynamic equation for the membrane fluctuation amplitude. The time derivative of the fluctuation amplitude  $h(\boldsymbol{q},t)$  (membrane velocity) should coincide with the normal velocity of the fluid at the membrane  $v_z(\boldsymbol{q},z=\bar{\ell},t)$  obtained from Eqs. (10) and (11) together with the four coefficients (see also the Appendix). Using the result of the

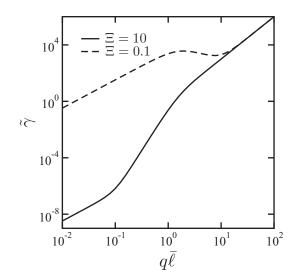


FIG. 2. Dimensionless decay rate  $\tilde{\gamma} \equiv \gamma \bar{t}$  [see Eq. (18)] with  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$  as a function of dimensionless wave number  $q\bar{\ell}$ . The solid and dashed lines represent  $\Xi = \xi/\bar{\ell} = 10$  and 0.1, respectively.

above hydrodynamic calculation, we can write the dynamic equation of h(q,t) as follows:

$$\frac{\partial h(\boldsymbol{q},t)}{\partial t} = -\gamma(q,\bar{\ell},\xi)h(\boldsymbol{q},t) 
+ \Lambda_x(q,\bar{\ell})V_{x0}(\boldsymbol{q},t) + \Lambda_z(q,\bar{\ell})V_{z0}(\boldsymbol{q},t) 
+ \zeta(\boldsymbol{q},t).$$
(17)

In the above,  $\gamma(q, \bar{\ell}, \xi)$  is the hydrodynamic decay rate

$$\gamma(q,\bar{\ell},\xi) = \Gamma(q,\bar{\ell})E(q,\xi),\tag{18}$$

where the kinetic coefficient  $\Gamma(q,\bar{\ell})$  is given by

$$\Gamma(q,\bar{\ell}) = \frac{1}{2\eta q} \frac{\sinh^2(q\bar{\ell}) - (q\bar{\ell})^2}{\sinh^2(q\bar{\ell}) - (q\bar{\ell})^2 + \sinh(q\bar{\ell})\cosh(q\bar{\ell}) + (q\bar{\ell})}. \tag{19}$$

The same expression was obtained by Seifert [26]. The second and the third terms on the r.h.s. of Eq. (17) are due to the wall boundary conditions Eqs. (7) and (8). Our calculation yields

$$\Lambda_x(q,\bar{\ell}) = \frac{-iq\bar{\ell}\sinh(q\bar{\ell})}{\sinh^2(q\bar{\ell}) - (q\bar{\ell})^2 + \sinh(q\bar{\ell})\cosh(q\bar{\ell}) + (q\bar{\ell})},$$
(20)

$$\Lambda_z(q,\bar{\ell}) = \frac{\sinh(q\bar{\ell}) + q\bar{\ell}\cosh(q\bar{\ell})}{\sinh^2(q\bar{\ell}) - (q\bar{\ell})^2 + \sinh(q\bar{\ell})\cosh(q\bar{\ell}) + (q\bar{\ell})}. \tag{21}$$

The last term in Eq. (17) represents the thermal white noise; its average vanishes  $\langle \zeta(\boldsymbol{q},t) \rangle = 0$  while its correlation is fixed by the fluctuation-dissipation theorem (FDT) [30,31]

$$\langle \zeta(\boldsymbol{q},t)\zeta(-\boldsymbol{q},t')\rangle = 2k_{\rm B}T\Gamma(q,\bar{\ell})\delta(t-t').$$
 (22)

# D. Hydrodynamic decay rate

We first introduce  $\bar{t} \equiv 4\eta \bar{\ell}^3/\kappa$  as a characteristic time. In Fig. 2 we plot the scaled decay rate  $\gamma(q,\bar{\ell},\xi)\bar{t}$  [see Eq. (18)] as a function of the dimensionless wave number  $q\bar{\ell}$  when

 $\Xi = \xi/\bar{\ell} = 10$  and 0.1. For our later discussion, it is useful here to discuss its asymptotic behaviors. We first note that the kinetic coefficient  $\Gamma(q,\bar{\ell})$  in Eq. (19) behaves as

$$\Gamma \approx \begin{cases} \bar{\ell}^3 q^2 / 12\eta, & q \ll 1/\bar{\ell} \\ 1/4\eta q, & q \gg 1/\bar{\ell}. \end{cases}$$
 (23)

Depending on the relative magnitude between  $\bar{\ell}$  and  $\xi$ , two different asymptotic behaviors of the decay rate can be distinguished [26]. For  $\bar{\ell} \ll \xi$  (corresponding to  $\Xi = 10$  in Fig. 2), the decay rate increases monotonically as

$$\gamma \approx \begin{cases}
\kappa \bar{\ell}^3 q^2 / 12 \eta \xi^4, & q \ll 1/\xi \\
\kappa \bar{\ell}^3 q^6 / 12 \eta, & 1/\xi \ll q \ll 1/\bar{\ell} \\
\kappa q^3 / 4 \eta, & 1/\bar{\ell} \ll q.
\end{cases}$$
(24)

The small-q behavior  $\gamma \sim q^2$  results from the conservation of the fluid volume between the membrane and the wall [32]. The dependence  $\gamma \sim q^6$  in the intermediate regime, where the effect of potential becomes irrelevant, was predicted by Brochard and Lennon [9]. For large q, we recover the behavior of a free membrane  $\gamma \sim q^3$ . All these asymptotic behaviors are observed in Fig. 2.

For  $\xi \ll \bar{\ell}$  (corresponding to  $\Xi = 0.1$  in Fig. 2), on the other hand,  $\gamma$  changes nonmonotonically as [26]

$$\gamma \approx \begin{cases}
\kappa \bar{\ell}^{3} q^{2} / 12 \eta \xi^{4}, & q \ll 1/\bar{\ell} \\
\kappa / 4 \eta \xi^{4} q, & 1/\bar{\ell} \ll q \ll 1/\xi \\
\kappa q^{3} / 4 \eta. & 1/\xi \ll q.
\end{cases}$$
(25)

While the small-q and large-q behaviors are unchanged from Eq. (24), here the decay rate decreases with increasing q in the intermediate range. This unusual decrease of the decay rate clearly appears for  $1 < q\bar{\ell} < 10$  in Fig. 2. Such an anomalous behavior occurs due to the fact that the potential confines the mean squared fluctuation amplitudes to  $\langle h^2 \rangle \approx k_{\rm B} T \xi^4 / \kappa$  independently of q [see Eq. (4)], while hydrodynamic damping becomes less effective with increasing q [26]. We also note that the absolute value of  $\gamma$  in the small-q region is sensitive to the value of  $\Xi$ , while it is independent of  $\Xi$  in the large-q region.

# III. MEMBRANE TWO-POINT CORRELATION FUNCTIONS

Using the result of the hydrodynamic calculation, we shall discuss in this section the two-point correlation functions of bound membrane [33,34]. We separately investigate the cases of (i) a static wall, (ii) an active wall, and (iii) an active wall with an intrinsic time scale.

## A. Static wall

In the case of a static wall, the velocities at the wall vanish in Eqs. (7) and (8), i.e.,  $V_{x0}(\boldsymbol{q},t) = V_{z0}(\boldsymbol{q},t) = 0$ . Hence Eq. (17) reduces to

$$\frac{\partial h(\boldsymbol{q},t)}{\partial t} = -\gamma(q,\bar{\ell},\xi)h(\boldsymbol{q},t) + \zeta(\boldsymbol{q},t), \tag{26}$$

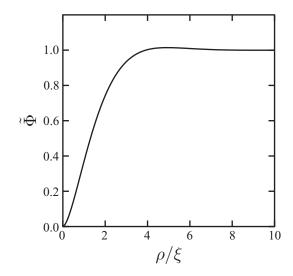


FIG. 3. Dimensionless static correlator  $\tilde{\Phi} \equiv (4\kappa/k_B T \xi^2)\Phi$  in the presence of a static wall [see Eq. (31)] as a function of dimensionless distance  $\rho/\xi$ . Notice that  $\tilde{\Phi}$  takes a maximum value at  $\rho/\xi = 4.93$ .

and one can easily solve for h(q,t) as

$$h(\boldsymbol{q},t) = h(\boldsymbol{q},0)e^{-\gamma(q,\bar{\ell},\xi)t} + \int_{0}^{t} dt_{1} \, \zeta(\boldsymbol{q},t_{1})e^{-\gamma(q,\bar{\ell},\xi)(t-t_{1})}.$$
 (27)

Using the above solution and Eq. (22), we calculate the membrane two-point correlation function which can be separated into two parts [33,34]:

$$\langle [h(\boldsymbol{\rho},t) - h(\boldsymbol{\rho}',0)]^2 \rangle = \Phi(\boldsymbol{\rho} - \boldsymbol{\rho}') + \phi(\boldsymbol{\rho} - \boldsymbol{\rho}',t), \quad (28)$$

where the translational invariance of the system has been assumed. In the above, the first term is a purely static correlator,

$$\Phi(\boldsymbol{\rho} - \boldsymbol{\rho}') = \langle [h(\boldsymbol{\rho}) - h(\boldsymbol{\rho}')]^2 \rangle 
= 2 \int \frac{d^2q}{(2\pi)^2} \langle h(\boldsymbol{q})h(-\boldsymbol{q}) \rangle [1 - e^{i\boldsymbol{q}\cdot(\boldsymbol{\rho} - \boldsymbol{\rho}')}], \quad (29)$$

describing the static membrane roughness, while the second term is a dynamical correlator,

$$\phi(\boldsymbol{\rho} - \boldsymbol{\rho}', t) = 2 \int \frac{d^2q}{(2\pi)^2} \langle h(\boldsymbol{q})h(-\boldsymbol{q}) \rangle e^{i\boldsymbol{q}\cdot(\boldsymbol{\rho} - \boldsymbol{\rho}')} \times [1 - e^{-\gamma(q,\bar{\ell},\xi)t}], \tag{30}$$

describing the propagation of fluctuations with a distance  $|\rho - \rho'|$ .

Using the static correlation function for h(q) in Eq. (4), we first calculate the static correlator

$$\Phi(\boldsymbol{\rho} - \boldsymbol{\rho}') = \frac{k_{\rm B}T}{\pi\kappa} \int_0^\infty dq \, \frac{q}{q^4 + \xi^{-4}} [1 - J_0(q|\boldsymbol{\rho} - \boldsymbol{\rho}'|)] 
= \frac{k_{\rm B}T\xi^2}{4\kappa} \left[ 1 - \frac{1}{\pi} G_{0,4}^{3,0} \left( \frac{(|\boldsymbol{\rho} - \boldsymbol{\rho}'|/\xi)^4}{256} \middle| 0, \frac{1}{2}, \frac{1}{2}, 0 \right) \right], \quad (31)$$

where  $J_0(z)$  is the zero-order Bessel function of the first kind, and the Meijer G function is used in the last expression [35]. In Fig. 3 we plot the scaled static correlator  $\Phi(\rho - \rho')$  as a function of  $\rho/\xi$  where  $\rho = |\rho - \rho'|$ . Only in this plot, we use

 $\xi$  to scale the length because the above static correlator is solely determined by the free energy in Eq. (2), and Eq. (31) does not depend on  $\bar{\ell}$ . In the large distance  $\rho/\xi \gg 1$ , the (route mean square) height difference between two points on the bound membrane is proportional to  $\xi$ . It is interesting to note that  $\Phi(\rho - \rho')$  changes nonmonotonically and shows a maximum around  $\rho/\xi \approx 4.93$ . A similar overshoot behavior of the membrane profile was reported previously [36].

As for the dynamical correlator in Eq. (30), we perform the angular integration and obtain the expression

$$\phi(\rho - \rho', t) = \frac{k_{\rm B}T}{\pi \kappa} \int_0^\infty dq \, \frac{q}{q^4 + \xi^{-4}} \times [1 - e^{-\gamma(q, \bar{\ell}, \xi)t}] J_0(q|\rho - \rho'|). \tag{32}$$

We first set  $\rho = \rho'$  and discuss the MSD of a tagged membrane segment given by [33,34]

$$\phi_0(t) = \frac{k_{\rm B}T}{\pi\kappa} \int_0^\infty dq \, \frac{q}{q^4 + \xi^{-4}} [1 - e^{-\gamma(q,\bar{\ell},\xi)t}], \qquad (33)$$

where we have used  $J_0(0)=1$ . Instead of the correlation length  $\xi$ , we hereafter use  $\bar{\ell}$  to scale the length. Note that the hydrodynamic effect is manifested by the appearance of the length  $\bar{\ell}$ . In Fig. 4 we plot the dimensionless MSD  $\phi_0$  as a function of  $t/\bar{t}$  (recall that  $\bar{t}=4\eta\bar{\ell}^3/\kappa$ ) for  $\Xi=10$  (monotonic damping case) and  $\Xi=0.1$  (nonmonotonic damping case), respectively. In order to find out the asymptotic behaviors clearly, we have also plotted an effective growth exponent  $\alpha$  defined by

$$\alpha(t) = \frac{d \ln \phi_0(t)}{d \ln t}.$$
 (34)

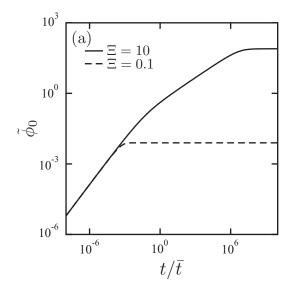
For both  $\Xi=10$  and 0.1, the MSD increases monotonically as a function of time. For  $\Xi=10$  ( $\bar{\ell}\ll\xi$ ), there are three different asymptotic regimes of the time dependence. In the small time regime ( $t\ll\bar{t}$ ), the MSD behaves as  $\phi_0\sim t^{2/3}$ , which corresponds to the diffusion of a free membrane [33,34]. This scaling behavior can be obtained by using the large-q behavior of the decay rate in Eq. (24):

$$\phi_0(t) \approx \frac{k_{\rm B}T}{\pi\kappa} \int_0^\infty dq \, \frac{1}{q^3} [1 - e^{-(\kappa q^3/4\eta)t}] \sim \frac{k_{\rm B}T}{\kappa^{1/3} \eta^{2/3}} t^{2/3}. \tag{35}$$

In the intermediate time regime  $(\bar{t} \ll t \ll \Xi^6 \bar{t})$ , we have  $\phi_0 \sim t^{1/3}$ , which stems from the intermediate-q behavior of  $\gamma$  in Eq. (24):

$$\phi_0(t) \approx \frac{k_{\rm B}T}{\pi\kappa} \int_0^\infty dq \, \frac{1}{q^3} [1 - e^{-(\kappa\bar{\ell}^3 q^6/12\eta)t}] \sim \frac{k_{\rm B}T\bar{\ell}}{\kappa^{2/3}\eta^{1/3}} t^{1/3}. \tag{36}$$

In this regime, as discussed by Brochard and Lennon [9], the conservation of the enclosed incompressible volume between the membrane and the wall is important, while the effect of the potential acting between them is irrelevant. The Fourier transform of the above expression, i.e., the power spectral density, was previously discussed by Gov *et al.* in Ref. [16]. In the long time regime ( $\Xi^6 \bar{t} \ll t$ ), the MSD saturates at the



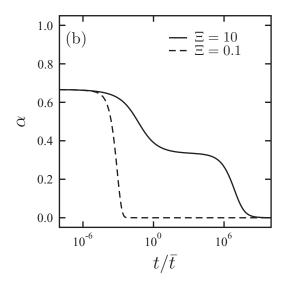


FIG. 4. (a) Dimensionless MSD of a tagged membrane segment  $\tilde{\phi}_0 \equiv (\pi \kappa / k_B T \bar{\ell}^2) \phi_0$  in the presence of a static wall [see Eq. (33)] as a function of dimensionless time  $t/\bar{t}$  where  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ . The solid and dashed lines represent  $\Xi = \xi/\bar{\ell} = 10$  and 0.1, respectively. (b) Effective exponent  $\alpha$  of the MSDs in (a) as defined in Eq. (34).

value given by

$$\phi_0(t \to \infty) \approx \left[\frac{k_{\rm B}T\bar{\ell}^2}{\pi\kappa}\right] \frac{\pi\Xi^2}{4} \sim \frac{k_{\rm B}T}{\kappa}\xi^2.$$
 (37)

For  $\Xi=0.1$  ( $\xi\ll\bar{\ell}$ ), on the other hand, there are only two asymptotic regimes. The MSD increases as  $\phi_0\sim t^{2/3}$  in the small time regime ( $t\ll\Xi^3\bar{t}$ ), whereas in the long time regime ( $\Xi^3\bar{t}\ll t$ ), it saturates at the value given by Eq. (37).

Let us consider then the case  $\rho \neq \rho'$ . In Fig. 5 we plot the scaled  $\phi(\rho - \rho', t)$  in Eq. (32) as a function of  $\rho/\bar{\ell}$  for different times when  $\Xi = 10$ . For all the cases, the dynamic correlator changes nonmonotonically and exhibits a typical undershoot behavior. The minimum of  $\phi$  occurs for larger  $\rho$  as time evolves. In the long time limit,  $t \to \infty$ ,  $\phi(\rho - \rho', t)$ 

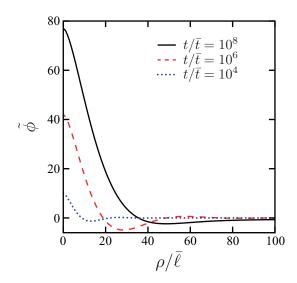


FIG. 5. Dimensionless dynamical correlator  $\tilde{\phi} \equiv (\pi \kappa / k_B T \bar{\ell}^2) \phi$ in the presence of a static wall [see Eq. (32)] as a function of dimensionless distance  $\rho/\bar{\ell}$  for  $t/\bar{t}=10^8$  (solid black),  $10^6$  (dashed red),  $10^4$  (dotted blue) when  $\Xi = \xi/\bar{\ell} = 10$ . Here the characteristic time is  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ .

in Eq. (32) coincides with the second term in Eq. (31) and is given by the Meijer G function.

#### B. Active wall

We now investigate the case when the wall is active so that it exerts random velocities on the ambient fluid. The membrane dynamics in the presence of an active wall is described by Eq. (17). This equation can be also solved for h(q,t) as

$$h(\boldsymbol{q},t) = h(\boldsymbol{q},0)e^{-\gamma(q,\bar{\ell},\xi)t}$$

$$+ \Lambda_{x}(q,\bar{\ell}) \int_{0}^{t} dt_{1} V_{x0}(\boldsymbol{q},t_{1})e^{-\gamma(q,\bar{\ell},\xi)(t-t_{1})}$$

$$+ \Lambda_{z}(q,\bar{\ell}) \int_{0}^{t} dt_{2} V_{z0}(\boldsymbol{q},t_{2})e^{-\gamma(q,\bar{\ell},\xi)(t-t_{2})}$$

$$+ \int_{0}^{t} dt_{3} \zeta(\boldsymbol{q},t_{3})e^{-\gamma(q,\bar{\ell},\xi)(t-t_{3})}.$$
(38)

The random velocities generated at the wall are assumed to have the following statistical properties:

$$\langle V_{x0}(\boldsymbol{\rho},t)\rangle = \langle V_{z0}(\boldsymbol{\rho},t)\rangle = 0, \tag{39}$$

$$\langle V_{x0}(\boldsymbol{\rho},t)V_{x0}(\boldsymbol{\rho}',t')\rangle = 2S_x\delta(\boldsymbol{\rho}-\boldsymbol{\rho}')\delta(t-t'), \tag{40}$$

$$\langle V_{z0}(\boldsymbol{\rho},t)V_{z0}(\boldsymbol{\rho}',t')\rangle = 2S_z\delta(\boldsymbol{\rho}-\boldsymbol{\rho}')\delta(t-t'), \tag{41}$$

$$\langle V_{x0}(\boldsymbol{\rho},t)V_{z0}(\boldsymbol{\rho}',t')\rangle = 0, \tag{42}$$

$$\langle V_{x0}(\boldsymbol{\rho},t)\zeta(\boldsymbol{\rho}',t')\rangle = \langle V_{z0}(\boldsymbol{\rho},t)\zeta(\boldsymbol{\rho}',t')\rangle = 0, \quad (43)$$

where we have introduced the amplitudes  $S_r$  and  $S_z$  in Eqs. (40) and (41), respectively. With these statistical properties, we can calculate the total two-point correlation function, which consists of the static and the dynamical parts as before:

$$\langle [h(\boldsymbol{\rho},t) - h(\boldsymbol{\rho}',0)]^2 \rangle_{\text{tot}} = \Phi_{\text{tot}}(\boldsymbol{\rho} - \boldsymbol{\rho}') + \phi_{\text{tot}}(\boldsymbol{\rho} - \boldsymbol{\rho}',t). \tag{44}$$

In the above total correlation function, the static correlator in the presence of the active wall becomes

$$\Phi_{\text{tot}}(\boldsymbol{\rho} - \boldsymbol{\rho}') = \frac{1}{\pi} \int_{0}^{\infty} dq \, q \left[ \frac{k_{\text{B}} T}{\kappa(q^{4} + \xi^{-4})} + \frac{S_{x} |\Lambda_{x}(q,\bar{\ell})|^{2}}{\gamma(q,\bar{\ell},\xi)} + \frac{S_{z} |\Lambda_{z}(q,\bar{\ell})|^{2}}{\gamma(q,\bar{\ell},\xi)} \right] [1 - J_{0}(q|\boldsymbol{\rho} - \boldsymbol{\rho}')]$$

$$\equiv \Phi(\boldsymbol{\rho} - \boldsymbol{\rho}') + \Phi_{x}(\boldsymbol{\rho} - \boldsymbol{\rho}') + \Phi_{z}(\boldsymbol{\rho} - \boldsymbol{\rho}'), \tag{45}$$

where  $\Lambda_x$  and  $\Lambda_z$  were obtained in Eqs. (20) and (21), respectively, while  $\Phi(\rho - \rho')$  was defined in Eq. (31) for the static wall case. In the above equations, we have defined two correlators  $\Phi_x$  and  $\Phi_z$ . On the other hand, the dynamical correlator in Eq. (44) is given by

$$\phi_{\text{tot}}(\boldsymbol{\rho} - \boldsymbol{\rho}', t) = \frac{1}{\pi} \int_0^\infty dq \, q \left[ \frac{k_{\text{B}} T}{\kappa(q^4 + \xi^{-4})} + \frac{S_x |\Lambda_x(q, \bar{\ell})|^2}{\gamma(q, \bar{\ell}, \xi)} + \frac{S_z |\Lambda_z(q, \bar{\ell})|^2}{\gamma(q, \bar{\ell}, \xi)} \right] [1 - e^{-\gamma(q, \bar{\ell}, \xi)t}] J_0(q | \boldsymbol{\rho} - \boldsymbol{\rho}' |). \tag{46}$$

By setting  $\rho = \rho'$ , the total MSD of a tagged membrane segment in the presence of the active wall becomes

$$\phi_{\text{tot}}(t) = \frac{1}{\pi} \int_0^\infty dq \, q \left[ \frac{k_{\text{B}} T}{\kappa(q^4 + \xi^{-4})} + \frac{S_x |\Lambda_x(q,\bar{\ell})|^2}{\gamma(q,\bar{\ell},\xi)} + \frac{S_z |\Lambda_z(q,\bar{\ell})|^2}{\gamma(q,\bar{\ell},\xi)} \right] [1 - e^{-\gamma(q,\bar{\ell},\xi)t}] \equiv \phi_0(t) + \phi_{x0}(t) + \phi_{z0}(t), \quad (47)$$

where the first term  $\phi_0(t)$  was defined before in Eq. (33) for the static wall case, while  $\phi_{x0}$  and  $\phi_{z0}$  have been newly defined here.

Before showing the result of MSD, we first discuss the wave-number dependencies of the quantities  $|\Lambda_x|^2/\gamma$ and  $|\Lambda_z|^2/\gamma$  appearing in Eqs. (45)–(47). These quantities originating from the active wall are plotted in Fig. 6 as a function of  $q\bar{\ell}$  for  $\Xi = 10$  and 0.1. Using the asymptotic behaviors of  $\gamma$ , as shown in Eqs. (24) and (25), we can obtain the limiting expressions for  $|\Lambda_x|^2/\gamma$  and  $|\Lambda_z|^2/\gamma$  as well. When  $\bar{\ell} \ll \xi$  (corresponding to  $\Xi = 10$ ), we have

$$|\Lambda_x|^2/\gamma \approx \begin{cases} 3\eta \xi^4/\kappa \bar{\ell}, & q \ll 1/\xi \\ 3\eta/\kappa \bar{\ell} q^4, & 1/\xi \ll q \ll 1/\bar{\ell} \\ 4\eta \bar{\ell}^2 e^{-2\bar{\ell}q}/\kappa q, & 1/\bar{\ell} \ll q, \end{cases}$$
(48)

$$|\Lambda_{x}|^{2}/\gamma \approx \begin{cases} 3\eta \xi^{4}/\kappa \bar{\ell}, & q \ll 1/\xi \\ 3\eta/\kappa \bar{\ell}q^{4}, & 1/\xi \ll q \ll 1/\bar{\ell} \end{cases}$$

$$4\eta \bar{\ell}^{2} e^{-2\bar{\ell}q}/\kappa q, & 1/\bar{\ell} \ll q,$$

$$|\Lambda_{z}|^{2}/\gamma \approx \begin{cases} 12\eta \xi^{4}/\kappa \bar{\ell}^{3}q^{2}, & q \ll 1/\xi \\ 12\eta/\kappa \bar{\ell}^{3}q^{6}, & 1/\xi \ll q \ll 1/\bar{\ell} \\ 4\eta \bar{\ell}^{2} e^{-2\bar{\ell}q}/\kappa q, & 1/\bar{\ell} \ll q. \end{cases}$$

$$(48)$$

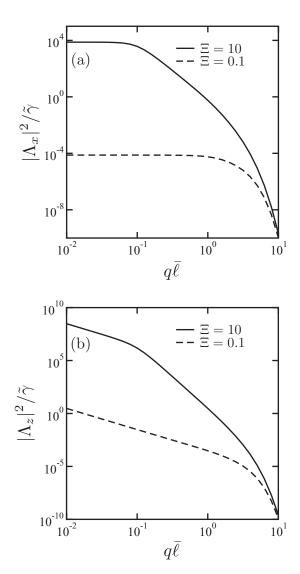


FIG. 6. Plots of (a)  $|\Lambda_x|^2/\tilde{\gamma}$  [see Eq. (20)] and (b)  $|\Lambda_z|^2/\tilde{\gamma}$  [see Eq. (21)] as a function of dimensionless wave number  $q\bar{\ell}$ . Here  $\tilde{\gamma} \equiv \gamma\bar{t}$  [see Eq. (18)] with  $\bar{t} = 4\eta\bar{\ell}^3/\kappa$  is the dimensionless decay rate. The solid and dashed lines represent  $\Xi = \xi/\bar{\ell} = 10$  and 0.1, respectively.

For  $\xi \ll \bar{\ell}$  (corresponding to  $\Xi=0.1$ ), on the other hand, we obtain

$$\begin{split} |\Lambda_{x}|^{2}/\gamma \approx \begin{cases} 3\eta \xi^{4}/\kappa \bar{\ell}, & q \ll 1/\bar{\ell} \\ 4\eta \xi^{4} \bar{\ell}^{2} q^{3} e^{-2\bar{\ell}q}/\kappa, & 1/\bar{\ell} \ll q \ll 1/\xi \\ 4\eta \bar{\ell}^{2} e^{-2\bar{\ell}q}/\kappa q, & 1/\xi \ll q, \end{cases} \\ |\Lambda_{z}|^{2}/\gamma \approx \begin{cases} 12\eta \xi^{4}/\kappa \bar{\ell}^{3} q^{2}, & q \ll 1/\bar{\ell} \\ 4\eta \xi^{4} \bar{\ell}^{2} q^{3} e^{-2\bar{\ell}q}/\kappa, & 1/\bar{\ell} \ll q \ll 1/\xi \\ 4\eta \bar{\ell}^{2} e^{-2\bar{\ell}q}/\kappa q. & 1/\xi \ll q. \end{cases} \tag{51} \end{split}$$

The static correlators  $\Phi_x$  and  $\Phi_z$  defined in Eq. (45) due to the active wall can now be obtained by performing numerical integrals. In Fig. 7 we plot the static correlators  $\Phi_x$  and  $\Phi_z$  as a function of  $\rho/\ell$  when  $\Xi=10$ . Here  $\Phi_x$  and  $\Phi_z$  are scaled by  $4\eta\bar{\ell}S_x/\pi\kappa$  and  $4\eta\bar{\ell}S_z/\pi\kappa$ , respectively. We notice that  $\Phi_x$  behaves similarly to that of the static wall case  $\Phi$  given in Eq. (31) and plotted in Fig. 3. On the other hand,  $\Phi_z$  diverges logarithmically for large  $\rho/\bar{\ell}$  because the integral is found to

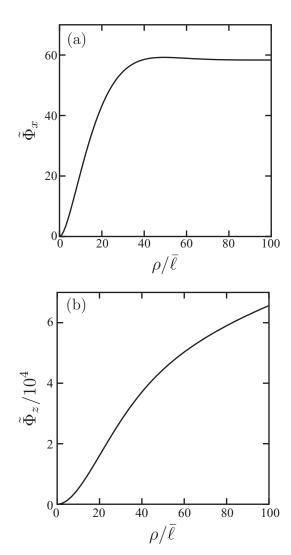


FIG. 7. Dimensionless static correlators (a)  $\tilde{\Phi}_x \equiv (\pi \kappa / 4\eta \bar{\ell} S_x) \Phi_x$  and (a)  $\tilde{\Phi}_z \equiv (\pi \kappa / 4\eta \bar{\ell} S_z) \Phi_z$  (divided by  $10^4$ ) in the presence of an active wall [see Eq. (45)] as a function of dimensionless distance  $\rho / \bar{\ell}$  when  $\Xi = \xi / \bar{\ell} = 10$ .

be infrared divergent. Such a logarithmic divergence is avoided when we consider a finite membrane size, which gives rise to a cutoff for small wave numbers in the integral of Eq. (45). It should be noted that both  $\Phi_x$  and  $\Phi_z$  depend on  $\bar{\ell}$  and  $\xi$ , while  $\Phi$  is solely determined by  $\xi$ . This means that  $\Phi_x$  and  $\Phi_z$  include the geometrical as well as the hydrodynamic effects.

In Figs. 8 and 9, we plot the scaled membrane MSD  $\phi_{x0}$  and  $\phi_{z0}$  [see Eq. (47)], respectively, as a function of  $t/\bar{t}$  when  $\Xi=10$  and 0.1. For  $\bar{\ell}\ll\xi$  (corresponding to  $\Xi=10$ ), there are three different asymptotic regimes both for  $\phi_{x0}$  and  $\phi_{z0}$ . In the small time regime ( $t\ll\bar{t}$ ), we have  $\phi_{x0}\sim t$  and  $\phi_{z0}\sim t$ , showing a normal diffusive behavior. This is because  $\phi_{x0}$  can be approximated as

$$\phi_{x0}(t) \approx \frac{4\eta \bar{\ell}^2 S_x}{\pi \kappa} \int_0^\infty dq \, e^{-2\bar{\ell}q} [1 - e^{-(\kappa q^3/4\eta)t}]$$

$$\approx \frac{\bar{\ell}^2 S_x t}{\pi} \int_0^\infty dq \, e^{-2\bar{\ell}q} q^3 \sim \frac{S_x}{\bar{\ell}^2} t. \tag{52}$$

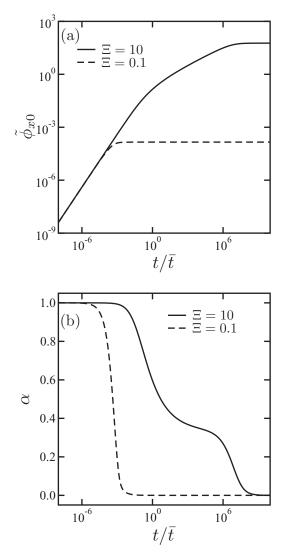


FIG. 8. (a) Dimensionless MSD of a tagged membrane segment  $\tilde{\phi}_{x0} \equiv (\pi \kappa/4\eta \bar{\ell} S_x)\phi_{x0}$  in the presence of an active wall [see Eq. (47)] as a function of dimensionless time  $t/\bar{t}$  where  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ . The solid and dashed lines represent  $\Xi = \xi/\bar{\ell} = 10$  and 0.1, respectively. (b) Effective exponent  $\alpha$  of the MSDs in (a) as defined in Eq. (34).

Notice that only small-q contributes to the integral, and the same holds for  $\phi_{z0}$ . In the intermediate time regime  $(\bar{t} \ll t \ll \Xi^6 \bar{t})$ , we have  $\phi_{x0} \sim t^{1/3}$  and  $\phi_{z0} \sim t^{2/3}$ , which can be essentially obtained by the integrals in Eqs. (36) and (35), respectively. In the long time regime  $(\Xi^6 \bar{t} \ll t)$ ,  $\phi_{x0}$  saturates at the value

$$\phi_{x0}(t \to \infty) \approx \left[ \frac{4\eta \bar{\ell} S_x}{\pi \kappa} \right] \frac{3\Xi^2}{8} \sim \frac{\eta \xi^2 S_x}{\kappa \bar{\ell}}.$$
 (53)

On the other hand,  $\phi_{z0}$  diverges logarithmically for  $t \to \infty$ , which can be seen in Fig. 9(a) and shown analytically. Such a divergence in time occurs for small q and can be avoided when the membrane size is finite as mentioned before.

For  $\xi \ll \bar{\ell}$  (corresponding to  $\Xi=0.1$ ), on the other hand, there are only two asymptotic regimes. The MSDs increase both linearly as  $\phi_{x0} \sim t$  and  $\phi_{z0} \sim t$  in the small time regime  $(t \ll \Xi^3 \bar{t})$ . In the long time regime  $(\Xi^3 \bar{t} \ll t)$ ,  $\phi_{x0}$  saturates at

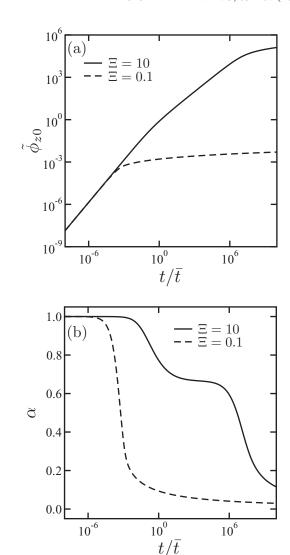


FIG. 9. (a) Dimensionless MSD of a tagged membrane segment  $\tilde{\phi}_{z0} \equiv (\pi \kappa/4\eta \bar{\ell} S_z) \phi_{z0}$  in the presence of an active wall [see Eq. (47)] as a function of dimensionless time  $t/\bar{t}$  where  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ . The solid and dashed lines represent  $\Xi = \xi/\bar{\ell} = 10$  and 0.1, respectively. (b) Effective exponent  $\alpha$  of the MSDs in (a) as defined in Eq. (34).

the value

$$\phi_{x0}(t \to \infty) \approx \left[ \frac{4\eta \bar{\ell} S_x}{\pi \kappa} \right] \frac{3\Xi^4}{8} \sim \frac{\eta \xi^4 S_x}{\kappa \bar{\ell}^3},$$
 (54)

while  $\phi_{z0}$  also diverges logarithmically as above.

### C. Active wall with an intrinsic time scale

Finally we consider a situation in which the activity of the wall occurs over a finite time scale  $\tau$ . In this case, the statistical properties of random velocities which have been given in Eqs. (40) and (41) would be replaced by the following exponential correlation function in time [19,20]:

$$\langle V_{x0}(\boldsymbol{\rho},t)V_{x0}(\boldsymbol{\rho}',t')\rangle = \frac{S_x}{\tau}\delta(\boldsymbol{\rho}-\boldsymbol{\rho}')e^{-|t-t'|/\tau}, \quad (55)$$

$$\langle V_{z0}(\boldsymbol{\rho},t)V_{z0}(\boldsymbol{\rho}',t')\rangle = \frac{S_z}{\tau}\delta(\boldsymbol{\rho}-\boldsymbol{\rho}')e^{-|t-t'|/\tau}, \quad (56)$$

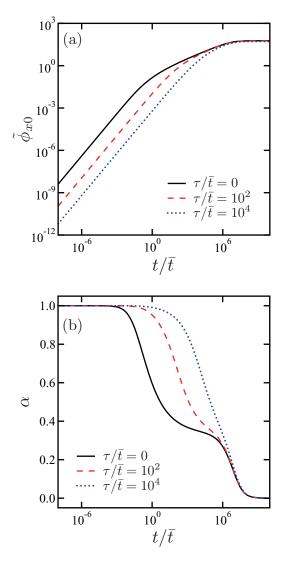


FIG. 10. (a) Dimensionless MSD of a tagged membrane segment  $\tilde{\phi}_{x0} \equiv (\pi \kappa/4\eta \bar{\ell} S_x)\phi_{x0}$  in the presence of an active wall with an intrinsic time scale [see Eq. (59)] as a function of dimensionless time  $t/\bar{t}$  where  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ . Different colors correspond to  $\tau/\bar{t} = 0$  (solid black),  $10^2$  (dashed red),  $10^4$  (dotted blue), and we set  $\Xi = 10$ . (b) Effective exponent  $\alpha$  of the MSDs in (a) as defined in Eq. (34).

while the other velocity correlations remain the same. In general, the intrinsic time scale  $\tau$  can be different between the x and z components. In the above relations, we have put a factor  $1/\tau$  so that the physical dimension of  $S_x$  and  $S_z$  is the same as before.

Repeating the same procedure as before, we obtain the total two-point correlation function, which can be also separated into the static and dynamics parts as in Eq. (44). The static correlators in the presence of the active wall now become

$$\Phi_{x}(\boldsymbol{\rho} - \boldsymbol{\rho}') = \frac{1}{\pi} \int_{0}^{\infty} dq \, q \, \frac{S_{x} |\Lambda_{x}(q, \bar{\ell})|^{2}}{\gamma(q, \bar{\ell}, \xi)[\gamma(q, \bar{\ell}, \xi)\tau + 1]} \times [1 - J_{0}(q|\boldsymbol{\rho} - \boldsymbol{\rho}'|)], \tag{57}$$

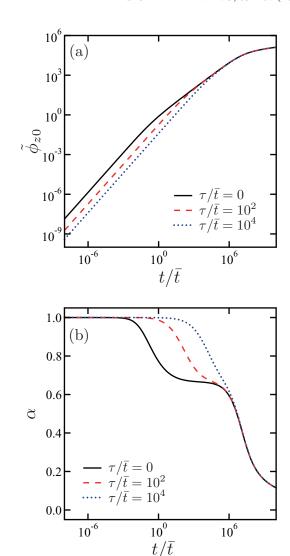


FIG. 11. (a) Dimensionless MSD of a tagged membrane segment  $\tilde{\phi}_{z0} \equiv (\pi \kappa/4\eta \bar{\ell} S_z)\phi_{z0}$  in the presence of an active wall with an intrinsic time scale [see Eq. (60)] as a function of dimensionless time  $t/\bar{t}$  where  $\bar{t} = 4\eta \bar{\ell}^3/\kappa$ . Different colors correspond to  $\tau/\bar{t} = 0$  (solid black),  $10^2$  (dashed red),  $10^4$  (dotted blue), and we set  $\Xi = 10$ . (b) Effective exponent  $\alpha$  of the MSDs in (a) as defined in Eq. (34).

$$\Phi_{z}(\boldsymbol{\rho} - \boldsymbol{\rho}') = \frac{1}{\pi} \int_{0}^{\infty} dq \, q \, \frac{S_{z} |\Lambda_{z}(q, \bar{\ell})|^{2}}{\gamma(q, \bar{\ell}, \xi)[\gamma(q, \bar{\ell}, \xi)\tau + 1]} \times [1 - J_{0}(q|\boldsymbol{\rho} - \boldsymbol{\rho}'|)]. \tag{58}$$

A similar static correlator was previously discussed by Gov et al. [19,20]. Notice that the above expressions reduce to those in Eq. (45) when  $\tau \to 0$ . This is reasonable because the exponential function in Eqs. (55) and (56) reduce to a  $\delta$  function in the limit of  $\tau \to 0$ .

Similarly, the two MSD functions of a tagged membrane segment are given by

$$\phi_{x0}(t) = \frac{1}{\pi} \int_0^\infty dq \, q \, \frac{S_x |\Lambda_x(q,\bar{\ell})|^2}{\gamma(q,\bar{\ell},\xi)[\gamma(q,\bar{\ell},\xi)\tau+1]} \times [1 - e^{-\gamma(q,\bar{\ell},\xi)t}], \tag{59}$$

$$\phi_{z0}(t) = \frac{1}{\pi} \int_0^\infty dq \, q \, \frac{S_z |\Lambda_z(q,\bar{\ell})|^2}{\gamma(q,\bar{\ell},\xi)[\gamma(q,\bar{\ell},\xi)\tau+1]} \times [1 - e^{-\gamma(q,\bar{\ell},\xi)t}], \tag{60}$$

which also reduce to those in Eq. (47) when  $\tau \to 0$ . In Figs. 10 and 11, we plot the scaled  $\phi_{x0}$  and  $\phi_{z0}$ , respectively, as a function of  $t/\bar{t}$  for different  $\tau$  values when  $\Xi=10$ . We first notice that both  $\phi_{x0}$  and  $\phi_{z0}$  decrease when the intrinsic time scale  $\tau$  is taken into account. Also the initial time regions during which  $\phi_{x0}$  and  $\phi_{z0}$  grow linearly in time increase for larger  $\tau$  values, and the regions showing the scaling  $\phi_{x0} \sim t^{1/3}$  or  $\phi_{z0} \sim t^{2/3}$  become narrower. In the large  $\tau$  limit, there will be only two scaling regimes of the MSDs.

#### IV. SUMMARY AND DISCUSSION

In this paper, we have discussed the dynamics of a membrane interacting with an active wall that generates random velocities. We have generally shown that the dynamics of a bound membrane is significantly affected by active fluctuations at the wall, and they propagate through the surrounding fluid. Using the result of the hydrodynamic calculation of a bound membrane, we have derived a dynamic equation for the membrane fluctuation amplitude [see Eq. (17)]. As noted by Seifert previously [26], there are two different asymptotic behaviors of the hydrodynamic decay rate  $\gamma$ depending on the relative magnitude between the average membrane-wall distance  $\bar{\ell}$  and the correlation length  $\xi$  [see Eqs. (24) and (25)]. We have obtained in Sec. III the membrane two-point correlation functions for three different wall cases: (i) a static wall, (ii) an active wall, and (iii) an active wall with an intrinsic time scale.

As a dynamic part of the correlation function, we have mainly discussed the MSD of a tagged membrane and investigated its asymptotic time dependencies for the different types of walls. For the static wall case, the membrane fluctuates due to thermal agitations. When the decay rate  $\gamma$  changes monotonically, the MSD given by Eq. (33) exhibits two asymptotic behaviors  $\phi_0 \sim t^{2/3}$  and  $\phi_0 \sim t^{1/3}$  before it reaches a constant value that is fixed by  $\xi$  (see Fig. 4). When the wall is active, on the other hand, the partial MSDs in Eq. (47) grow linearly in time,  $\phi_{x0} \sim \phi_{z0} \sim t$ , in the early stage. Compared to the dynamics due to thermal fluctuations, this is a unique behavior of a membrane segment in the presence of an active wall (see Figs. 8 and 9). When the active wall has a finite intrinsic time scale  $\tau$  as defined in Eqs. (55) and (56), the linear-growth region of the MSD is further extended as  $\tau$  is increased.

The present work should be distinguished from those dealing with the dynamics of "active membranes" [8]. These membranes contain active proteins such as ion pumps which consume the chemical energy and drive the membrane out of equilibrium. Being motivated by the theoretical predictions [37–43], some experiments have shown that active forces enhance membrane fluctuations [44–46]. In our theory, we have considered that the active components are incorporated not in the membrane but in the wall, and we discussed their hydrodynamic effects on the membrane fluctuations. Hence our work is related to the recent work by Maitra *et al.* [47]

who discussed the dynamics of a membrane coupled to an actin cortex consisting of filaments with active stresses and currents.

For our further discussion, we give here some numerical estimates of the quantities used in our calculations. As an example, we consider the shape fluctuations of RBCs. Previously, the data for a normal RBC [48] were well described by using the following parameters [19,20];  $\kappa \sim 10^{-19}$  J,  $\bar{\ell} \sim 2-3 \times 10^{-8}$  m, and  $\xi \sim 2-3 \times 10^{-7}$  m. Then the important dimensionless parameter is roughly  $\Xi = \xi/\bar{\ell} \sim 10$  for RBCs, and the decay rate  $\gamma$  is expected to increase monotonically as in Eq. (24). Using the value of water viscosity  $\eta \sim 10^{-3}$  J/m³, we obtain the characteristic time scale as  $\bar{t} = 4\eta\bar{\ell}^3/\kappa \sim 10^{-7}$  s. Hence the second crossover time scale discussed in Eq. (36) is roughly given by  $\Xi^6\bar{t} \sim 10^{-1}$  s. Since  $\bar{t}$  and  $\Xi^6\bar{t}$  are well separated, the three different asymptotic regimes of  $\phi_0(t)$  should be clearly observable.

The intrinsic time scale  $\tau$  appearing in Eqs. (55) and (56) represents the duration of force production at the active wall and can be roughly estimated as  $\tau \sim 10^{-3}$  s for the spectrin network of RBCs [19,20]. Hence the choice of  $\tau/\bar{t} \sim 10^4$  in Figs. 10 or 11 is reasonable. Moreover, the force balance between the spectrin compression and the membrane bending yields a characteristic length scale of the order of  $L \sim 10^{-7}$  m. From the viewpoint of dimensional analysis, the quantities  $S_x$  and  $S_z$ , which fix the amplitudes of the random velocities in Eq. (40) and (41), respectively, can be evaluated as  $S_x \sim L^4/\tau \sim 10^{-24}$  m<sup>4</sup>/s and similarly for  $S_z$ . With this value, the amplitude of the MSD due to the active wall becomes  $\phi_{x0} \sim \eta \bar{\ell} S_x/\kappa \sim 10^{-17}$  m<sup>2</sup>. This value is comparable to that of thermal fluctuations  $\phi_0 \sim k_B T \bar{\ell}^2/\kappa \sim 10^{-16}$  m<sup>2</sup>.

As mentioned in Sec. II, the decay rate  $\gamma$  changes nonmonotonically when  $\Xi \ll 1$ . This situation may occur for a charged membrane pushed by an osmotic pressure [26]. When unscreened electrostatic interactions compete with an osmotic pressure, the condition  $\Xi \ll 1$  is met whenever  $\bar{\ell} \gg \kappa \ell_B/k_B T \sim 5 \times 10^{-9}$  m where  $\ell_B$  is the Bjerrum length. As the unbinding transition point is approached [28],  $\bar{\ell}$  becomes much larger than  $\xi$ .

Following the calculation by Seifert [26], we have shown in Sec. II that the hydrodynamic kinetic coefficient  $\Gamma(q,\bar{\ell})$  is given by Eq. (19). In Ref. [17], Gov *et al.* used different boundary conditions at the membrane and obtained an alternative expression for the kinetic coefficient:

$$\Gamma_{\rm G}(q,\bar{\ell}) = \frac{e^{-2q\bar{\ell}}}{4\eta q} [e^{2q\bar{\ell}} - 1 - 2q\bar{\ell} - 2(q\bar{\ell})^2]. \tag{61}$$

As expressed in Eq. (14), Seifert and we have used an incompressibility condition for the fluid near the membrane, whereas Gov *et al.* employed a zero-shear-stress condition, which implies that the *xz* component of the shear on both sides of the membrane are equal. Gov *et al.* insisted that the latter condition is appropriate for a fluid membrane which cannot support shear stress across its width [17]. We have quantitatively compared Eqs. (19) and (61) and confirmed that they only differ by a numerical factor of 4 in the small-*q* regime, and the asymptotic scaling behaviors are completely

identical. Notice that  $\Gamma_G(q, \bar{\ell})$  in Eq. (61) behaves as

$$\Gamma_{\rm G} \approx \begin{cases} \bar{\ell}^3 q^2 / 3\eta, & q \ll 1/\bar{\ell} \\ 1/4\eta q, & q \gg 1/\bar{\ell}, \end{cases}$$
 (62)

which can be compared with Eq. (23). In any case, the differences between Eqs. (19) and (61) are not significant as far as the role of the wall is concerned, and various scaling behaviors of the MSD discussed in this paper are valid.

In this paper, we have only dealt with a tensionless membrane whose shape is governed by Eq. (1). In Ref. [16], it was claimed that the attachment of the cytoskeleton to the membrane would induce an effective surface tension. For a membrane with a finite surface tension  $\Sigma$ , the free energy is modified to

$$F = \int d^2 \rho \left[ \frac{\kappa}{2} (\nabla^2 \ell)^2 + V(\ell) + \frac{\Sigma}{2} (\nabla \ell)^2 \right]. \tag{63}$$

Hence the quantity E in the static correlation function Eq. (4) should now be replaced with

$$E(q,\xi) = \kappa(q^4 + \xi^{-4}) + \Sigma q^2. \tag{64}$$

The new term associated with the surface tension neither modifies the small wave number nor the large wave number asymptotic behaviors [26]. Although a more complicated crossover behavior can arise in the intermediate wave number if  $\Sigma > \kappa/\xi^2$ , we do not discuss it here because our main aim is to see the effects of the active wall. In general, the presence of the finite surface tension tends to suppress the membrane fluctuations.

In our model, the outer fluid is assumed to be purely viscous characterized by a constant viscosity  $\eta$ . It should be noted, however, fluids surrounding biomembranes are viscoelastic rather than purely viscous. This is a common situation in all eukaryotic cells whose cytoplasm is a soup of proteins and organelles, including a thick submembrane layer of actin-meshwork forming a part of the cell cytoskeleton [12]. The extra-cellular fluid can also be viscoelastic because it is filled with extracellular matrix or hyaluronic acid gel. In order to mimic the real situations, the dynamics of undulating bilayer membrane surrounded by viscoelastic media was considered before [49,50]. It was assumed that both sides of the membrane are occupied by viscoelastic media with a frequency-dependent modulus that obeys a power-law behavior  $G(\omega) = G_0(i\omega)^{\beta}$  with  $0 \le \beta \le 1$  [49–52]. Such a frequency dependence is commonly observed for various polymeric solutions at high frequencies. The limits of  $\beta = 0$ and 1 correspond to the purely elastic and purely viscous cases, respectively. Following the previous results, we argue that the time dependencies of MSD which has been expressed as  $\phi_0 \sim t^{lpha}$  in the pure viscous case will be modified to  $\phi_0 \sim t^{lpha eta}$  for both the static and the active wall cases. Hence the asymptotic exponent of the MSD is generally smaller than that for a purely viscous fluid.

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# APPENDIX: SOLUTIONS OF HYDRODYNAMIC EQUATIONS

The incompressibility condition Eq. (5) and the Stokes equation (6) can be formally solved for the fluid velocity v in terms of the force f acting on the fluid [53]:

$$v_{x}(\boldsymbol{q},z) = \int_{-\infty}^{\infty} dz' \frac{e^{-q|z-z'|}}{4\eta q} [(1-q|z-z'|) f_{x}(\boldsymbol{q},z') + iq(z'-z) f_{z}(\boldsymbol{q},z')], \tag{A1}$$

$$v_y(\boldsymbol{q},z) = \int_{-\infty}^{\infty} dz' \, \frac{e^{-q|z-z'|}}{4\eta q} 2f_y(\boldsymbol{q},z'), \tag{A2}$$

$$v_z(\boldsymbol{q}, z) = \int_{-\infty}^{\infty} dz' \frac{e^{-q|z-z'|}}{4\eta q} [(1+q|z-z'|) f_z(\boldsymbol{q}, z') + iq(z'-z) f_x(\boldsymbol{q}, z')], \tag{A3}$$

with  $q = |\mathbf{q}|$ . Notice that  $v_y$  in Eq. (A2) is not coupled to the other components and hence can be neglected.

For the fluid in the region  $0 \le z \le \overline{\ell}$ , the forces are acting both at z = 0 and  $z = \overline{\ell}$  so that  $f_x$  and  $f_z$  can be written as

$$f_x(\boldsymbol{q},z) = f_x(\boldsymbol{q},0)\delta(z) + f_x(\boldsymbol{q},\bar{\ell})\delta(z-\bar{\ell}), \quad (A4)$$

$$f_z(\boldsymbol{q},z) = f_z(\boldsymbol{q},0)\delta(z) + f_z(\boldsymbol{q},\bar{\ell})\delta(z-\bar{\ell}). \tag{A5}$$

Substituting Eqs. (A4) and (A5) into Eq. (A3), we obtain Eq. (10) where the the coefficients A and B are given by

$$A = \frac{e^{-q\bar{\ell}}}{2\eta q} \left[ iq\bar{\ell} f_x(\boldsymbol{q},\bar{\ell}) + (1+q\bar{\ell}) f_z(\boldsymbol{q},\bar{\ell}) \right], \tag{A6}$$

$$B = \frac{e^{-q\bar{\ell}}}{2nq} \left[ -i(1 - q\bar{\ell}) f_x(\boldsymbol{q}, \bar{\ell}) + q\bar{\ell} f_z(\boldsymbol{q}, \bar{\ell}) \right]. \tag{A7}$$

For the fluid in the region  $\bar{\ell} \leqslant z$ , the forces are acting only at  $z = \bar{\ell}$  so that  $f_x$  and  $f_z$  can be written as

$$f_x(\boldsymbol{q},z) = f_x(\boldsymbol{q},\bar{\ell})\delta(z-\bar{\ell}),$$
 (A8)

$$f_z(\boldsymbol{q}, z) = f_z(\boldsymbol{q}, \bar{\ell})\delta(z - \bar{\ell}). \tag{A9}$$

Substituting Eqs. (A8) and (A9) into Eq. (A3), we obtain Eq. (11) where the coefficients C and D are given by

$$C = \frac{f_z(\boldsymbol{q}, \ell)}{4\eta q},\tag{A10}$$

$$D = \frac{f_z(\boldsymbol{q}, \bar{\ell}) - i f_x(\boldsymbol{q}, \bar{\ell})}{4\eta q}.$$
 (A11)

Using these four coefficients A, B, C, and D, the x component of the velocity  $v_x^{\pm}(\boldsymbol{q},z,t)$  and the pressure  $p^{\pm}(\boldsymbol{q},z,t)$  are obtained as follows:

$$v_x^{-}(\mathbf{q}, z, t) = -i Aqz \sinh(qz) + i B[\sinh(qz) + qz \cosh(qz)] + (1 - qz)V_{x0}(\mathbf{q}, t)e^{-qz} - i qzV_{z0}(\mathbf{q}, t)e^{-qz},$$
(A12)

$$v_r^+(q,z,t) = -ie^{-q(z-\bar{\ell})}(C-D-Dq\bar{\ell}+Dqz),$$
 (A13)

$$p^{-}(q,z,t) = -2\eta q [A\cosh(qz) - B\sinh(qz)] + 2\eta q [V_{z0}(q,t) - iV_{x0}(q,t)]e^{-qz}, \quad (A14)$$

$$p^{+}(\boldsymbol{q},z,t) = 2\eta Dq e^{-q(z-\bar{\ell})}.$$
 (A15)

The four unknown coefficients are determined by the boundary conditions (12), (13), (14), and (15) at  $z = \bar{\ell}$ .

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